### UAV (aka drone) Forensics

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### Who We Are

- David Kovar
  - Commercial UAV owner/pilot
  - Ex Big 4 Cyber security investigator, Incident response consultant
- Greg Dominguez
  - Personal UAV owner/Pilot
  - Retired Air Force Computer Crime Investigator, Ex-Big 4 Investigator, former COO of forensic hardware firm
- Cindy Murphy
  - Cellphone Forensicator extraordinaire
- With thanks to Cellebrite for technical assistance





# Why is the Relevant?

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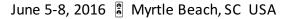


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# Market Growth and Jobs

- FAA Drone sales are expected to grow from 2.5 million this year to 7 million in 2020
- AUVSI's The Economic Impact of Unmanned Aircraft Systems Integration in the United States report shows the economic benefit of UAS integration. AUVSI's findings show that in the first three years of integration more than 70,000 jobs will be created in the United States with an economic impact of more than \$13.6 billion. This benefit will grow through 2025 when we foresee more than 100,000 jobs created and economic impact of \$82 billion.
- According to OpenSecrets.org, which tracks the influence of Washington lobbyists, spending by groups pushing for drone legalization has exploded from \$35 million in 2011 to \$184 million last year
- 20,000 DJI drones sold per month







# Illegal and inappropriate activity

- Drug delivery over US/Mexico border
- Drug and weapon delivery to prison
- Multiple invasions of privacy
- Flight above crowds and in controlled airspace
- Flight into operators and bystanders





# If You Are in Law Enforcement

- "There is evidence of a considerable increase in the unauthorized use of small, inexpensive Unmanned Aircraft Systems (UAS) by individuals and organizations, including companies. The FAA retains the responsibility for enforcing Federal Aviation Regulations, including those applicable to the use of UAS. The agency recognizes though that State and local Law Enforcement Agencies (LEA) are often in the best position to deter, detect, immediately investigate, and, as appropriate, pursue enforcement actions to stop unauthorized or unsafe UAS operations."
- <u>https://www.faa.gov/uas/regulations\_policies/media/FAA\_UAS-</u> <u>PO\_LEA\_Guidance.pdf</u>

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# **Anti-drone Solutions**

- RF fingerprinting
- Jamming
- Geo-fencing and no fly zones
- Tangle-drone Drops net over drone
- Shotguns
- Debris and game jerseys
- Lasers





# Terminology

- UAS Unmanned Aerial System Emphasis on system
- UAV Unmanned Aerial Vehicle The aircraft portion of the system
- GCS Ground Control Station The flight control portion of the system. May include manual and automatic control features
- Data link radio system to transmit data to and from the UAV. Often used for telemetry, sensor data, and FPV operation
- Drone Common term for any UAV but most often used to describe quads and other multirotor UAVs
- FPV First Person View technology that enables the operator to fly the UAV from the perspective of the UAV





#### Drone Forensics – High Altitude View

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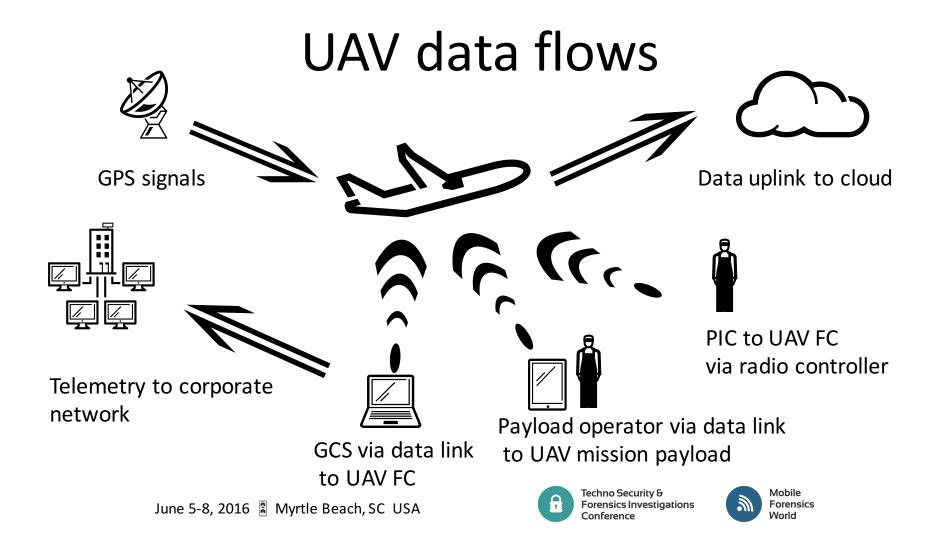
### UAV workflow

Mission Planning	Approval	Execution	Analysis	Delivery	
▶ Criteria	Business	<ul> <li>Logistics</li> </ul>	<ul> <li>Data validation</li> </ul>	Product	
▶ Airframe	<ul> <li>Site logistics</li> </ul>	<ul> <li>Site logistics</li> <li>Flight crew</li> </ul>	<ul> <li>Product</li> </ul>	delivery	
▶ Payload	<ul> <li>Safety</li> </ul>	<ul> <li>Weather</li> </ul>	generation	<ul> <li>Product support</li> </ul>	
,	► Legal	▶ Flight	▶ Quality	Lessons learned	
<ul> <li>Operator</li> </ul>	► Risk	operations	assurance	<ul> <li>Reporting</li> </ul>	
Location				▶ Billing	
<ul> <li>Time frame</li> </ul>	<ul> <li>Flight operations</li> </ul>			U U	
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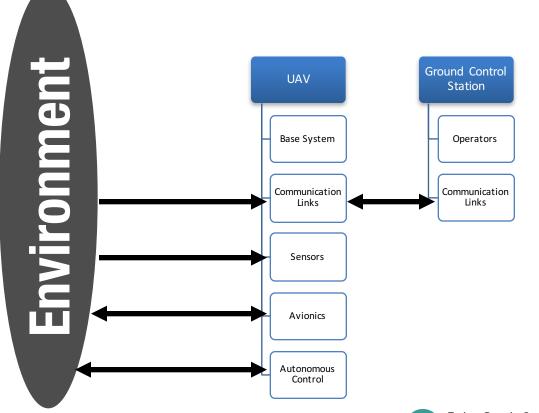
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#### **Operator, UAV, Environment Flows**



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# DJI Phantom 3 – Example UAV

- Very common UAV
- Relatively easy to hack
- SDK available
- Demonstrates all the major components





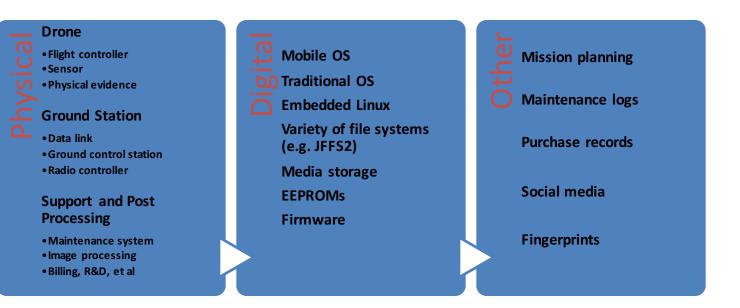
## **Connecting Evidence is Hard**

"There is no SN number for the entire product, however, there is SN number for different components. So you could use one component SN number as the unique identifier such as Flight Controller SN number." - DII





#### **UAV Forensic Artifacts**







# **Physical Artifacts**

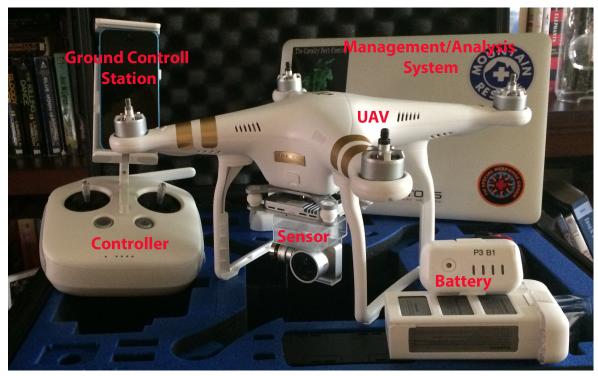
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#### What Physical Evidence is Available?



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### Phantom 2 vs Phantom 3



P76DCG3 0016047

These are just serial numbers.

No easy way to trace a hull to an individual

P77DCG3 0017004



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SZ DJI TECHNOLOGY CO., LTD

### Systems

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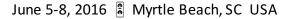
# UAV CPUs & "operating systems"

The flight controller is the core system in a UAS and amounts to the aircraft's CPU & operating system.

**Open Source** 

- > Openpilot
- Ardupilot (APM, Pixihawk)
- Multiwii
- ➢ KKmultipcopter

- Commercial
- Parrot AR Drone FC
- Naza (DJI)
- > Wookong (DJI)
- Dualsky (FC450, etc)
- Airware is trying to be the Microsoft/IBM of the UAV world, selling hardware and software that they hope is the defacto standard for flight controllers.
  - Linux is the predominant OS for onboard UAV systems







# UAV Exam – SDKs and Live UAV

- Most of the flight data is in RAM and most of the flight controller software is running off of flash media. Very little useful data persists after power is removed other than sensor data on the removable media.
- Similar to many other "normal" systems, APIs and SDKs exist for UAVs.
- Most commercial UAV applications will not extract all of the data an analyst needs.

• Be prepared to develop your own investigative tools using SDKs.

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# UAV Exam – SDKs and Live UAV

• Battery:

{designedVolume=5200|fullChargeVolume=5200|currentElectricity=4141|currentVolt age=11876|currentCurrent=-

961 | remainLifePercent=100 | remainPowerPercent=79 | batteryTemperature=20 | discharg eCount=2 | }

• MC:

{satelliteCount=6.0|homeLocationLatitude=40.4314293|homeLocationLongitude=-89.3118089000002|phantomLocationLatitude=40.4314619|phantomLocationLongitude= -89.31181570000001|velocityX=0.0|velocityY=0.0|velocityZ=-1.0|speed=0.1|altitude=-8.31500244140625|pitch=0.0|roll=-1.0|yaw=-120.0|remainPower=11878.0|remainFlyTime=0.0|powerLevel=2.0|isFlying=false|noFl yStatus=0.0|noFlyZoneCenterLatitude=0.0|noFlyZoneCenterLongitude=0.0|noFlyZone Radius=0.0|}





# **JTAG Analysis**

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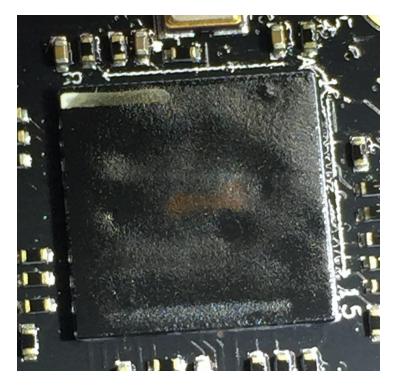
### Short Answer – Not Much Success

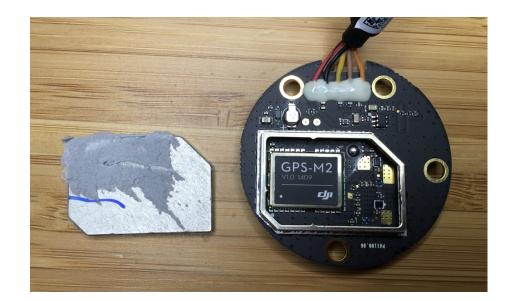
- Some chips are sealed
- Data may not persist across reboots
- Further analysis required





#### The Internals – MCU and GPS





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# Log Analysis

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### UAV Exam – Data Logging (Black Box)

- Many flight controllers, PixHawk for example, have data logging capabilities included
- Others, such as the DJI Naza, require an off board data logger
- Some ground control station applications have data logging capabilities

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# Phantom 3 Logs

- The Phantom 3 series (Professional, Advanced and Standard) create very similar logs
  - UAV Flight Data Recorder creates FLY???.DAT files
  - The GCS or DJI GO.app creates
     DJIFLightRecord\_date/time.TXT files
  - The ??? are a 3 digit sequence number
  - The logs will have a Date Time stamp



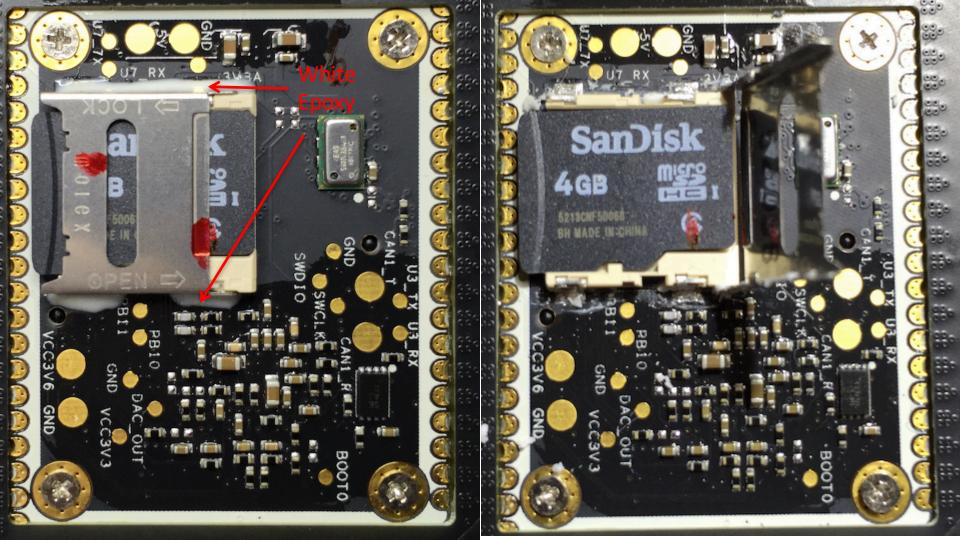


# Phantom 3 Log Collection

- FLY???.DAT
  - Are stored on a 4GB microSD card on the bottom side of the Main Board inside the UAV
  - The UAV will push oldest .DAT out for newest
  - To remove the card the UAV must opened up
    - Not a simple task, but doable
    - Video link: <u>https://www.youtube.com/watch?v=MNQUQ8p9IGE</u>







### FLY???.DAT

- Remove the micro SD Card and image it
- Extract the .DAT file with the most recent date
- Use DatCon.exe a FREE application from Rowland Johnson <u>https://datfile.net</u>
- DatCon will extract a mountain of information
  - Mostly Flight Data (GPS, battery, motor, altitude, etc)
  - DatCon is designed to assist in crash cause determination





- Runs on PC, Mac, Linux
- DatCon converts the Flight Data Record from the UAV
- You have a bit of latitude in what it gives you
- You may want to run it a few times with different settings
- For Instance selecting "Recording Start" gives you data starting before GPS Lock that includes the UAV serial number or "MC ID:"

• • •			0	DatCon			
File Help							
		LY LOG/FLY024.DAT r/Documents/DJi Pha	ntom/DJI Fo	prensics/David/	DATCo	nverter	View It
O Re	– time axis 0 cording Start otor Start ght Start	point	csv	<ul><li>.CSV</li><li>Event Lo</li></ul>		Sample Rate 30 C Hz 24.csv Imn in .csv)	View It
() Mc	cording Start otor Start S Lock	Upper 50.618 30371 Motor Stop Recording Stop	Log File	S Event Log Config L		FLY024.log.txt FLY024.config.txt	View It View It
Dashware Not Dashware compatible Make It Dashware Compatible			KML	KML File O Ground T	rack	24.kml Home Point Elevation from Go	View It
Cs		olumes/DJI FLY LO sers/wanderer/Doc			I Fore	nsics/David/DATConverte	er I
		lsers/wanderer/Doc	uments/DJ	i Phantom/DJ	I Fore	nsics/David/DATConverte	۲.





# DatCon

• The MCID will look like: MC ID :03Z0303948

- 12482 :
- It will be about 5 lines from the bottom of the file
- This number is also on a label on the Main Controller on the main board

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- FYI The number is also in the DJIFlightRecord\_2016-03-27\_[10-06-08].txt
  - Created by the DJI GO.app
- And it is on the mobile device in various applications



# DatCon

- DatCon creates the following files
  - FLY???.csv (huge very detailed spreadsheet)
  - FLY???.kml (if you ask it to) used to plug into Google Earth to see the flight track
  - FLY???.log.txt
  - FLY???.config.txt (Configuration log contains MC ID)





### FLY???.csv

- Seriously detailed Data
  - Over 100 columns of data
- GPS coordinates will give interesting location data
- Primary purpose is to log all flight data like a real "BLACK BOX"
  - Battery voltage, Battery load
  - Motor load, motor speed, etc
- Data may show a crash was a system failure, not an intentional act.





205	5900	9.833	0	0	0	7	205.0844	0		0	0.00370012
206	5921	9.868	0	0	0	7	204.82642	0		0	0.00369795
207	5942	9.903	0	0	0	7	204.9422	0		0	0.00418394
208	5963	9.938	0	0	0	7	205.78519	0		0	0.00306508
209	5984	9.973	0	0	0	7	204.53592	0		0	0.00353689
210	6005	10.008	0	0	0	7	205.88269	0		0	0.0035738
211	6026	10.043	0	0	0	7	205.88269	0		0	0.0035738
212	6047	10.078	0	-89.311684	40.4314889	7	204.73094	204.73094		0	0.00481765
213	6068	10.113	0	-89.311684	40.4314889	7	204.83455	204.96506		0	0.00347734
214	6089	10.148	0	-89.311684	40.4314889	7	205.32309	204.9676		0	0.00364866
215	6110	10.183	0	-89.311684	40.4314889	7	205.30276	204.96878		0	0.00454843
216	6131	10.218	0	-89.311684	40.4314889	7	204.79594	204.97665		0	0.00495827
217	6152	10.253	0	-89.311684	40.4314889	7	205.01433	204.9794		0	0.00442651
218	6172	10.287	0	-89.311682	40.431489	7	204.99197	204.98044	0.26354837	0	0.00417114
219	6194	10.323	0	-89.311682	40.431489	7	205.59831	204.98344	0.26719138	0	0.00399192
220	6215	10.358	0	-89.311682	40.431489	7	205.22356	204.98784	0.2704626	0	0.00451291
221	6236	10.393	0	-89.311682	40.4314892	7	204.58975	204.99129	0.27081573	0	0.00460048
222	6257	10.428	0	-89.311682	40.4314892	7	205.058	204.99225	0.27109057	0	0.00432047
223	6278	10.463	0	-89.311681	40.4314891	7	205.51707	204.99295	0.27339354	0	0.00467972
224	6299	10.498	0	-89.311681	40.4314891	7	205.13417	204.99583	0.27404606	0	0.00415297
225	6320	10.533	0	-89.311681	40.4314891	7	204.26878	204.99767	0.2747182	0	0.00359667
226	6341	10.568	0	-89.311681	40.4314891	7	204.87111	205.00235	0.2806532	0	0.0045848



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### **Event Log**

- Shows what amounts to a Boot sequence
- Shows Board: "wm320v2"
   wm320 is one of the Professional model numbers
- Shows the Battery barcode: 6171153003445
  - It is on the battery, the serial number is not on the battery
  - Also, has First Home Point Lat & Long





# **Configuration Log**

- More boot/initialization information
- The important piece in this text file is the MC ID: or UAV Serial Number
  - This is not the serial number on the outside of the UAV or on the Retail Box
  - It ties the physical airframe to the logs to the mobile device





- Recorded by the GCS app (DJI Go.app)
- Data is sent from UAV
- Has Flight data similar to the Flight Record – Just not as much
- Can contain images and video
- Also contains the MC ID number



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- Photos can be carved manually with Winhex Header: 0xFFD8FFE000104A464946
   EOF: 0xFFD9
  - EOF: 0xFFD9
- All of the JPG files are together at the bottom of the file
- Still dissecting the data fields





- There is an online parser:
   <u>http://healthydrones.com</u>
- Remember this is online and you are sending them the file
- Will allow you to download the .csv and kml
- Has other information also

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- Healthy Drones view
- Shows the flight path
- Shows the plane name
- Shows other data in the other categories
- The address may even be in the Details section



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- Offline Free analysis tool
- TXTlogToCSVtool by ferraript

http://www.phantompilots.com/threads/tool-win-offline-txt-flightrecord-to-csvconverter.70428/

- Again, you will get the .csv and the photos
- This tool was developed for files created on Android devices so iOS created files may be slightly different





### Getting the Files

- Image the SMART Device as you normally would to get the .txt files from the app
- Open the UAV, remove the microSD Card and Image
- The UAV may also be put in Flight Data Mode
- Show the mount for Mac

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#### The Answer is Often in the Data

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#### Sensor and Sensor Data

- The type of sensor will tell you a lot about the purpose of the flight
  - > LIDAR
  - Optical

  - Thermal
  - ≻ WiFi
- The sensor data will tell you a lot about where it has been, particularly since GPS data is critical for most types of missions





#### Sensors – Optical

#### Most common sensor out there

- Consumer GoPro, DJI, Canon, Sony
- Pro-sumer and professional

#### Artifacts

- The image
- The EXIF data

#### Location

Right there on the UAV – pull the SD card

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#### Sensors – EXIF Data

#### The purpose of a camera is to take a picture, and EXIF data tells a story about the camera and where it was taking pictures.

•	Image Description	: DCIM\100MEDIA\DJI_0030.JPG
•	Make	: DJI
•	Camera Model Name	: FC300S
•	Date/Time Original	: 2016:03:27 10:15:57
•	Create Date	: 2016:03:27 10:15:57
•	GPS Version ID	: 3.2.0.0
•	GPS Latitude Ref	: North
•	GPS Longitude Ref	: West
•	GPS Altitude Ref	: Above Sea Level
•	Aperture	: 2.8
•	GPS Altitude	: 74.6 m Above Sea Level
•	GPS Latitude	: 40 deg 32' 15.84" N
•	GPS Longitude	: 89 deg 30' 50.63" W
•	GPS Position	: 40 deg 32' 15.84" N, 89 deg 30' 50.63" W

DJI Phantoms do not did not record altitude in the EXIF data unfortunately

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#### Sensors – EXIF Data



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#### Sensor Data - Cloud

#### Consumer

- YouTube
- Facebook
- Etc
- Commercial
  - Data Mapper
  - Airware
  - Vendor specific

Question: Where are the credentials for uploading the imagery data to the cloud?





### **Evidence Beyond the UAV**

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### UAS Exam – Launch Point Evidence

#### **Ground Control Station**

- Often a mobile device combined with a radio controller
- Vendor applications and community developed
- Looking for:
  - Default settings
  - Launch points, dates
  - Owner name, account

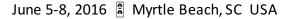
#### **Other Items**

- Spare removable media
- Other UAVs
- Laptops, cell phones, tablets



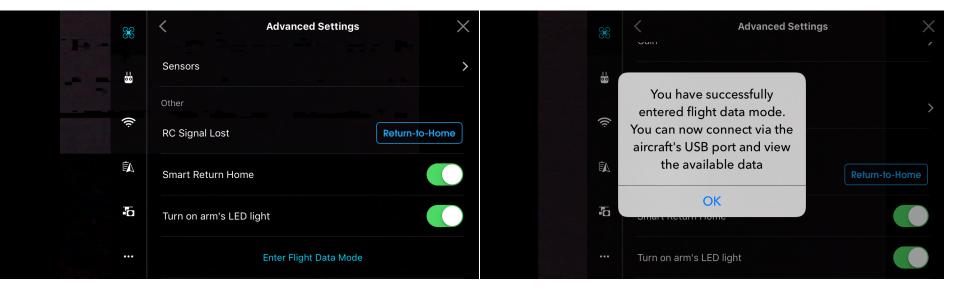


- You need the UAV, The RC and a device with the DJI Go.app
- Once all 3 are connected go to the Advanced Settings section of the GO.app
- Select Flight Data Mode













- Once in FDM you can connect UAV to a PC
- Yes, you will want to use a USB Write Blocker
- The UAV will mount and you can image the microSD card with your choice of tools
- While the UAV is in Flight Data Mode it will beep and it is loud

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- If you do not have a USB write Blocker you can direct connect
- Just make sure you document your actions.
- To get the FAT32 microSD card to mount in Mac OS X use the command line:

sudo hdiutil attach /dev/disk1s1 -shadow ~/Desktop/shadow

- No matter how you connect the UAV to a computer the transfer will be very slow (approx USB 1.1 speed)
- It will take an hour to image the 4GB micoSD card

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#### UAS Exam – Ground Control Station

Application configuration files contain interesting information

#### Drone Deploy:

- ajs\_user\_id
- %22dkovar%40kovarllc.com%22

#### Pix4D:

- 2016-03-27 10:34:03 [V] [WaypointCustomMissionDJI3::87] create wp at (4x.xxx689,-8x.xxx918) altitude: 50.000000
- displayBtnLogout(YES, username: <u>dkovar@gmail.com</u>)
- 2016-03-27 11:25:24 [D] [AppDelegate::38]

#### DJI Pilot:

- kUserDefaultKeyAircraftLocation 4x.xxx448,-8x.xxx675,-1577 (My house)
- com.facebook.sdk:serverConfiguration1383125992006153 <62706c69 73743030 ...>





#### UAS Exam – Remember that MC ID?

./com.dji.pilot/Documents/.device/history & ./com.dji.pilot/Library/Preferences/com.dji.pilot.plist

<string>03Z0303948&amp;02.04.10.07</string></plist>com.facebook.sdk:serverConfiguration1383125992006153 -<62706c69 73743030 ...>

statistics.db

- {user=Anonymous&apptype=0&appversion=2522&**devicetype=2**&deviceversion=01.07.00.00&devicesn=7130333511&productype=3&createtime=1459090198.971318&guid=F7F0A647-B460-41AD-B876-AD971E6079C1
- {user=Anonymous&apptype=0&appversion=2522&**devicetype=1**&deviceversion=02.04.10.07&devicesn=**03Z0303948**&prod uctype=3&createtime=1459090197.770736&guid=A8B53105-8B50-4F36-AAC9-3C5C09D5023D
- {user=Anonymous&apptype=0&appversion=2522&**devicetype=0**&deviceversion=01.22.40.95&devicesn=04CLA51862&productype=3&createtime=1459090196.597396&guid=9C244F41-6F0A-4767-9930-78C74CED66FFÅ;
- {user=Anonymous&apptype=0&appversion=2522&**devicetype=2**&deviceversion=01.07.15.01&devicesn=5443003511&productype=3&createtime=1459095943.455033&guid=CDB1637E-E9D7-458E-B859-0FD3DC007ACC

Devicetype=1 – Airframe Devicetype=2 – Battery Devicetype=3 – Camera

Airframe tied to camera tied to multiple batteries tied to a mobile device tied to log files tied to images.

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#### We've traced the UAV back home

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#### UAS Exam – Home & Office Evidence

Maintenance, logging & business systems

- Flight and maintenance logs, often with date/time/location/aircraft
- Client & accounting data

Data analysis system

- If not cloud based, this will have a lot of disk, CPU, and RAM •
- Historical sensor data •

Other

- UAVs, spare parts
- Spare removable media
- Other GCS



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#### Analysis of Other UAVs

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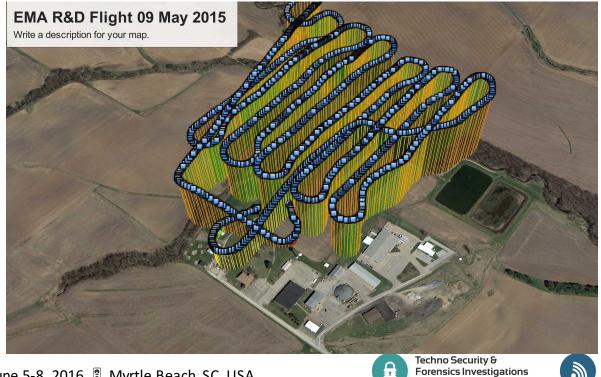
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#### UAVs with PixHawk Flight Controller

The following was created in under two minutes using Mission Planner



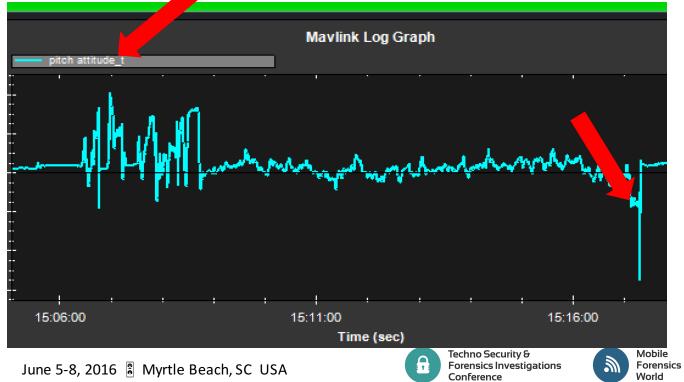
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#### UAVs with PixHawk Flight Controller

And this is what a crash looks like ....



#### UAVs with PixHawk Flight Controller

And all flight parameters are easily collected

FS_BATT_MAH       0         MIS_RESTART       0         AFS_WP_COMMS       0         INS_ACCOFFS_Z       -0.3554053         AFS_ENABLE       0         RLL2SRV_I       0.1         PTCH2SRV_TCONST       0.5         EKF_WIND_PNOISE       0.1         PTCH2SRV_TCONST       0.5         EKF_WIND_PNOISE       0.1         RNGFND_OFFSET       0         BATT2_MONITOR       0         FBWB_ELEV_REV       0         TERRAIN_ENABLE       1         ALT_HOLD_RTL       10000         ELEVON_OUTPUT       0         ARMING_REQUIRE       0         RLL2SRV_D       0.1         RCMAP_PITCH       2         EKF_GYRQ_PNOISE       0.015         SR0_EXTRA3       2         AFS_TERM_PIN       -1         RELAY_DEFAULT       0         SR0_POSITION       3         AUTO_FBW_STEER       0         ALT_OFFSET       0         TECS_LAND_ARSPD       -1         FORMAT_VERSION       13         BATT2_VOLT_PIN       2         AHRS_GPS_MINSATS       6         RALLY_TOTAL       0 </th <th></th> <th></th>		
AFS_WP_COMMS       0         INS_ACCOFFS_Z       -0.3554053         AFS_ENABLE       0         RLL2SRV_I       0.1         PTCH2SRV_TCONST       0.5         EKF_WIND_PNOISE       0.1         RNGFND_OFFSET       0         BATT2_MONITOR       0         FBWB_ELEV_REV       0         TERRAIN_ENABLE       1         ALT_HOLD_RTL       10000         ELEVON_OUTPUT       0         ARMING_REQUIRE       0         RCMAP_PITCH       2         EKF_GYRO_PNOISE       0.015         SR0_EXTRA3       2         AFS_TERM_PIN       -1         RELAY_DEFAULT       0         SR0_POSITION       3         AUTO_FFSET       0         TECS_LAND_ARSPD       -1         FORMAT_VERSION       13         BATT2_VOLT_PIN       2         AHRS_GPS_MINSATS       6         RALLY_TOTAL       0	FS_BATT_MAH	0
INS_ACCOFFS_Z       -0.3554053         AFS_ENABLE       0         RLL2SRV_I       0.1         PTCH2SRV_TCONST       0.5         EKF_WIND_PNOISE       0.1         RNGFND_OFFSET       0         BATT2_MONITOR       0         FBWB_ELEV_REV       0         TERRAIN_ENABLE       1         ALT_HOLD_RTL       10000         ELEVON_OUTPUT       0         ARMING_REQUIRE       0         RCMAP_PITCH       2         EKF_GYRO_PNOISE       0.015         SR0_EXTRA3       2         AFS_TERM_PIN       -1         RELAY_DEFAULT       0         SR0_POSITION       3         AUT0_FFBE       0         TECS_LAND_ARSPD       -1         FORMAT_VERSION       13         BATT2_VOLT_PIN       2         AHRS_GPS_MINSATS       6         RALLY_TOTAL       0	MIS_RESTART	0
AFS_ENABLE       0         RLL2SRV_I       0.1         PTCH2SRV_TCONST       0.5         EKF_WIND_PNOISE       0.1         RNGFND_OFFSET       0         BATT2_MONITOR       0         FBWB_ELEV_REV       0         TERRAIN_ENABLE       1         ALT_HOLD_RTL       10000         ELEVON_OUTPUT       0         ARMING_REQUIRE       0         RCMAP_PITCH       2         EKF_GYRO_PNOISE       0.015         SR0_EXTRA3       2         AFS_TERM_PIN       -1         RELAY_DEFAULT       0         SR0_POSITION       3         AUTO_FBW_STEER       0         ALT_OFFSET       0         TECS_LAND_ARSPD       -1         FORMAT_VERSION       13         BATT2_VOLT_PIN       2         AHRS_GPS_MINSATS       6         RALLY_TOTAL       0	AFS_WP_COMMS	0
RLL2SRV_I       0.1         PTCH2SRV_TCONST       0.5         EKF_WIND_PNOISE       0.1         RNGFND_OFFSET       0         BATT2_MONITOR       0         FBWB_ELEV_REV       0         TERRAIN_ENABLE       1         ALT_HOLD_RTL       10000         ELEVON_OUTPUT       0         ARMING_REQUIRE       0         RCMAP_PITCH       2         EKF_GYRO_PNOISE       0.015         SR0_EXTRA3       2         AFS_TERM_PIN       -1         RELAY_DEFAULT       0         SR0_POSITION       3         AUTO_FBW_STEER       0         ALT_OFFSET       0         TECS_LAND_ARSPD       -1         FORMAT_VERSION       13         BATT2_VOLT_PIN       2         AHRS_GPS_MINSATS       6         RALLY_TOTAL       0		-0.3554053
PTCH2SRV_TCONST 0.5 EKF_WIND_PNOISE 0.1 RNGFND_OFFSET 0 BATT2_MONITOR 0 FBWB_ELEV_REV 0 TERRAIN_ENABLE 1 ALT_HOLD_RTL 10000 ELEVON_OUTPUT 0 ARMING_REQUIRE 0 RLL2SRV_D 0.1 RCMAP_PITCH 2 EKF_GYR0_PNOISE 0.015 SR0_EXTRA3 2 AFS_TERM_PIN -1 RELAY_DEFAULT 0 SR0_POSITION 3 AUT0_FBW_STEER 0 ALT_OFFSET 0 TECS_LAND_ARSPD -1 FORMAT_VERSION 13 BATT2_VOLT_PIN 2 AHRS_GPS_MINSATS 6 RALLY_TOTAL 0		-
EKF_WIND_PNOISE       0.1         RNGFND_OFFSET       0         BATT2_MONITOR       0         FBWB_ELEV_REV       0         TERRAIN_ENABLE       1         ALT_HOLD_RTL       10000         ELEVON_OUTPUT       0         ARMING_REQUIRE       0         RCMAP_PITCH       2         EKF_GYRO_PNOISE       0.015         SR0_EXTRA3       2         AFS_TERM_PIN       -1         RELAY_DEFAULT       0         SR0_POSITION       3         AUTO_FBW_STEER       0         ALT_OFFSET       0         TECS_LAND_ARSPD       -1         FORMAT_VERSION       13         BATT2_VOLT_PIN       2         AHRS_GPS_MINSATS       6         RALLY_TOTAL       0		
RNGFND_OFFSET       0         BATT2_MONITOR       0         FBWB_ELEV_REV       0         TERRAIN_ENABLE       1         ALT_HOLD_RTL       10000         ELEVON_OUTPUT       0         ARMING_REQUIRE       0         RCMAP_PITCH       2         EKF_GYRO_PNOISE       0.015         SR0_EXTRA3       2         AFS_TERM_PIN       -1         RELAY_DEFAULT       0         SR0_POSITION       3         AUT0_FBW_STEER       0         TECS_LAND_ARSPD       -1         FORMAT_VERSION       13         BATT2_VOLT_PIN       2         AHRS_GPS_MINSATS       6         RALLY_TOTAL       0		
BATT2_MONITOR       0         FBWB_ELEV_REV       0         TERRAIN_ENABLE       1         ALT_HOLD_RTL       10000         ELEVON_OUTPUT       0         ARMING_REQUIRE       0         RLL2SRV_D       0.1         RCMAP_PITCH       2         EKF_GYR0_PNOISE       0.015         SR0_EXTRA3       2         AFS_TERM_PIN       -1         RELAY_DEFAULT       0         SR0_POSITION       3         AUT0_FBW_STEER       0         ALT_OFFSET       0         TECS_LAND_ARSPD       -1         FORMAT_VERSION       13         BATT2_VOLT_PIN       2         AHRS_GPS_MINSATS       6         RALLY_TOTAL       0		
FBWB_ELEV_REV       0         TERRAIN_ENABLE       1         ALT_HOLD_RTL       10000         ELEVON_OUTPUT       0         ARMING_REQUIRE       0         RCMAP_PITCH       2         EKF_GYRO_PNOISE       0.015         SR0_EXTRA3       2         AFS_TERM_PIN       -1         RELAY_DEFAULT       0         SR0_POSITION       3         AUTO_FBW_STEER       0         ALT_OFFSET       0         TECS_LAND_ARSPD       -1         FORMAT_VERSION       13         BATT2_VOLT_PIN       2         AHRS_GPS_MINSATS       6         RALLY_TOTAL       0		•
TERRAIN_ENABLE       1         ALT_HOLD_RTL       10000         ELEVON_OUTPUT       0         ARMING_REQUIRE       0         RL12SRV_D       0.1         RCMAP_PITCH       2         EKF_GYRO_PNOISE       0.015         SR0_EXTRA3       2         AFS_TERM_PIN       -1         RELAY_DEFAULT       0         SR0_POSITION       3         AUTO_FBW_STEER       0         ALT_OFFSET       0         TECS_LAND_ARSPD       -1         FORMAT_VERSION       13         BATT2_VOLT_PIN       2         AHRS_GPS_MINSATS       6         RALLY_TOTAL       0		-
ALT_HOLD_RTL       10000         ELEVON_OUTPUT       0         ARMING_REQUIRE       0         RLL2SRV_D       0.1         RCMAP_PITCH       2         EKF_GYRO_PNOISE       0.015         SR0_EXTRA3       2         AFS_TERM_PIN       -1         RELAY_DEFAULT       0         SR0_POSITION       3         AUTO_FBW_STEER       0         ALT_OFFSET       0         TECS_LAND_ARSPD       -1         FORMAT_VERSION       13         BATT2_VOLT_PIN       2         AHRS_GPS_MINSATS       6         RALLY_TOTAL       0		-
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RLL2SRV_D       0.1         RCMAP_PITCH       2         EKF_GYRO_PNOISE       0.015         SR0_EXTRA3       2         AFS_TERM_PIN       -1         RELAY_DEFAULT       0         SR0_POSITION       3         AUTO_FBW_STEER       0         ALT_OFFSET       0         FORMAT_VERSION       13         BATT2_VOLT_PIN       2         AHRS_GPS_MINSATS       6         RALLY_TOTAL       0		-
RCMAP_PITCH2EKF_GYRO_PNOISE0.015SR0_EXTRA32AFS_TERM_PIN-1RELAY_DEFAULT0SR0_POSITION3AUTO_FBW_STEER0ALT_OFFSET0TECS_LAND_ARSPD-1FORMAT_VERSION13BATT2_VOLT_PIN2AHRS_GPS_MINSATS6RALLY_TOTAL0		-
EKF_GYRO_PNOISE 0.015 SR0_EXTRA3 2 AFS_TERM_PIN -1 RELAY_DEFAULT 0 SR0_POSITION 3 AUTO_FBW_STEER 0 ALT_OFFSET 0 TECS_LAND_ARSPD -1 FORMAT_VERSION 13 BATT2_VOLT_PIN 2 AHRS_GPS_MINSATS 6 RALLY_TOTAL 0		
SR0_EXTRA32AFS_TERM_PIN-1RELAY_DEFAULT0SR0_POSITION3AUTO_FFW_STEER0ALT_OFFSET0TECS_LAND_ARSPD-1FORMAT_VERSION13BATT2_VOLT_PIN2AHRS_GPS_MINSATS6RALLY_TOTAL0		
AFS_TERM_PIN -1 RELAY_DEFAULT 0 SR0_POSITION 3 AUTO_FBW_STEER 0 ALT_OFFSET 0 TECS_LAND_ARSPD -1 FORMAT_VERSION 13 BATT2_VOLT_PIN 2 AHRS_GPS_MINSATS 6 RALLY_TOTAL 0		
RELAY_DEFAULT 0 SR0_POSITION 3 AUTO_FBW_STEER 0 ALT_OFFSET 0 TECS_LAND_ARSPD -1 FORMAT_VERSION 13 BATT2_VOLT_PIN 2 AHRS_GPS_MINSATS 6 RALLY_TOTAL 0		-
SR0_POSITION 3 AUT0_FBW_STEER 0 ALT_OFFSET 0 TECS_LAND_ARSPD -1 FORMAT_VERSION 13 BATT2_V0LT_PIN 2 AHRS_GPS_MINSATS 6 RALLY_TOTAL 0		-
AUTO_FBW_STEER 0 ALT_OFFSET 0 TECS_LAND_ARSPD -1 FORMAT_VERSION 13 BATT2_VOLT_PIN 2 AHRS_GPS_MINSATS 6 RALLY_TOTAL 0		-
ALT_OFFSET 0 TECS_LAND_ARSPD -1 FORMAT_VERSION 13 BATT2_VOLT_PIN 2 AHRS_GPS_MINSATS 6 RALLY_TOTAL 0		-
TECS_LAND_ARSPD -1 FORMAT_VERSION 13 BATT2_VOLT_PIN 2 AHRS_GPS_MINSATS 6 RALLY_TOTAL 0		-
FORMĀT_VERSION 13 BATT2_VOLT_PIN 2 AHRS_GPS_MINSATS 6 RALLY_TOTAL 0		-
BATT2_VOLT_PIN 2 AHRS_GPS_MINSATS 6 RALLY_TOTAL 0		
AHRS_GPS_MINSATS 6 RALLY_TOTAL 0		
RALLY_TOTAL 0		-
		-





#### **Closing Thoughts**

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Techno Security & **Forensics Investigations** Conference



Forensics

# **Challenges & Solutions**

- Data and command & control moving from WiFi to Bluetooth to dedicated radio to LTE & 4G
  - Harder to hack, easier to triangulate and identify with existing tools
- Many vendors, lots of variety, embedded systems
- Focus on ground control stations and post processing systems, analyze the sensor data. They tell 80% of the story

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#### **Closing Thoughts - Forensics**

The UAV is paired with controller

&

The UAV is also paired with ground control station

#### Means unique IDs

#### Means forensic evidence linking devices

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# **Closing Thoughts - Forensics**

- We needed to analyze the following to cover the entire system: ٠
- Three different versions of Linux •
- **IOS or Android** •
- **OS X or Windows** •
- 6+ file systems ٠
- ser2net •
- Wifi or Bluetooth or 915Mhz data link •
- EXIF •
- GPS •
- "Social media" •
- SDK •

#### No single UAV analysis tool





#### Future Work

- Develop stand alone versions of all tools
- Further JTAG analysis
- Further file analysis using above tools
- Facebook and other social media integration
- Other platforms
- Staying current





# **Closing Thoughts**

- Cybersecurity:
- The proper term for drones is sUAS small unmanned aerial system. Take a system approach to security and investigations, do not treat the vehicle as a discreet or standalone element.
- Law & Policy:
- UAVehicle. Apply law and policy to the risk/threat posed by the sensors and services rather than by the delivery mechanism
- Federal agencies using UAVs should consider Federal guidance on data protection and retention <u>http://www.justice.gov/file/441266/download</u>



